"Light-mesh" time division multiplexing for CWDM/DWDM networks

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Apology

- This presentation is about a Light-Mesh architecture
- Sorry for the "messy" extended abstract on the conference CD

Outline

Goal

Provide

- full mesh connectivity and
- sub-wavelength bandwidth granularity

in circuit switched all optical network.

- Overview of Existing Solutions
- The Light-Mesh Architecture
- Feasibility of Light-Mesh Configuration
- Optimal Resource Allocation in a Light Mesh

Connectivity in All Optical Networks: Light-path

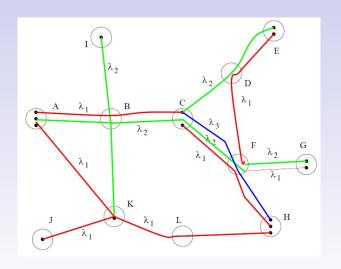


Figure Source:



S. Q. Zheng, A. Gumaste. SMART: An Optical Infrastructure for Future Internet

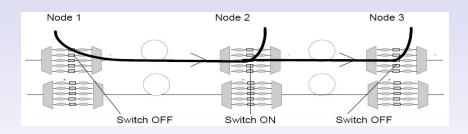
Connectivity in All Optical Networks: Light-tree

Establishes multicast tree topology with the use of "optical splitter".

Laxman H. Sahasrabuddhe, Biswanath Mukherjee, *Light-Trees: Optical Multicasting for Improved Performance in Wavelength-Routed Networks*. IEEE Communications Magazine
Feb. 1999

Light-trails

- A light path allowing traffic injection and dropping at intermediate nodes
- It is done by time division multiplexing at the nodes.



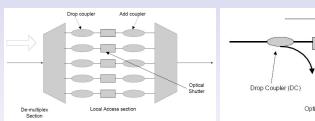
Ashwin Gumaste.

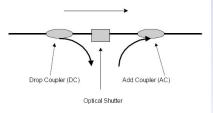
Light-trail and Light-frame Architectures for Optical Networks.

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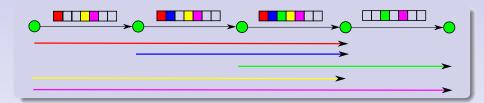


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Light-trails (synchronization)



- A cyclic time frame containing k slots established at each link
- Each demand is assigned to one of the slots
 - We assume uniform demands
- The time frames must be synchronized along the light trail
 - It's easy

Question

How the demand → slot assignment should be made?

Light-trails

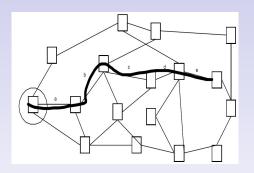
Advantages

- Technologically feasible (it is on the market)
- Allows higher or full connectivity by overcoming the limitation imposed by number of available wavelengths
- No need for (optical) packet header processing
 - No packet processing delay
- No need for (optical) buffers
 - No buffering delay
 - No packet loss due to buffer overflow
- Energy efficient

Limitations

- Still shows scalability problems
- Constrains the feasible network configuration
 - may make the network resource management more difficult
- Static resource allocation

Extended Light-Trail I: Trail splitting

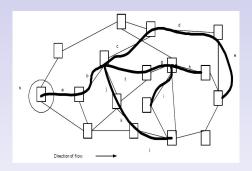




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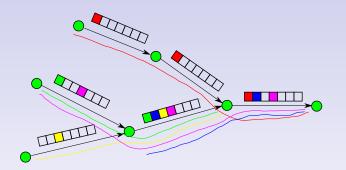
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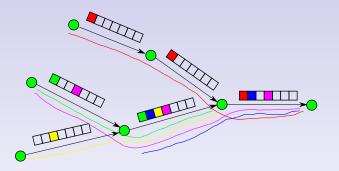


- Implemented by applying additional optical splitters
- No significant additional technical difficulty
- A. Gumaste.

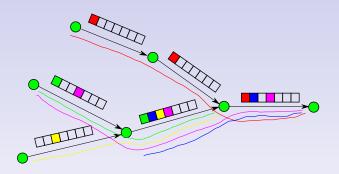
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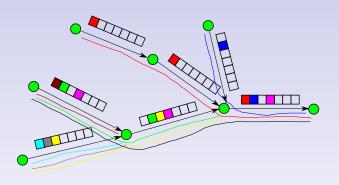




- The time frame synchronization is more difficult
 - Backward propagation of the synchronicity is necessary



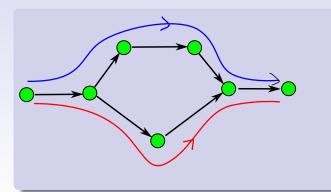
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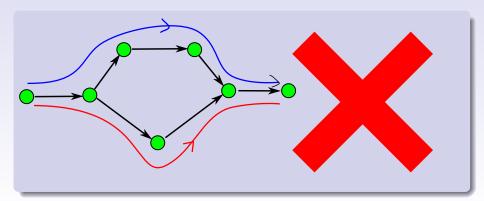
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- Allows complex single wavelength topologies.
- Overdetermined (cyclic) dependency may appear in the frame synchronicity
 - ⇒ not all configurations are feasible
- It isn't trivial which are the feasible topologies

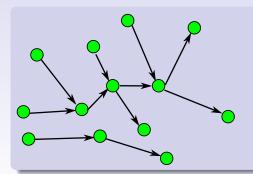
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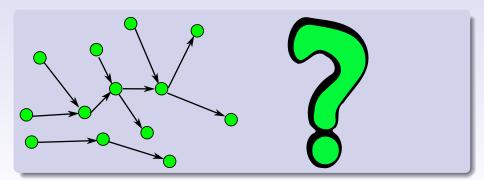
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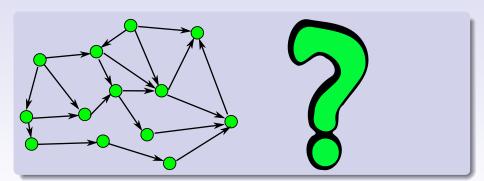
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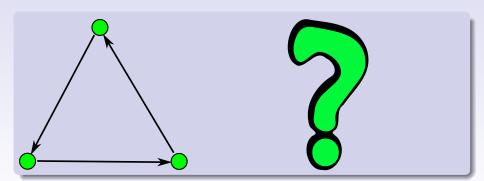
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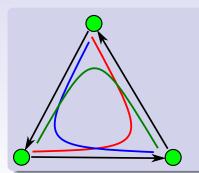
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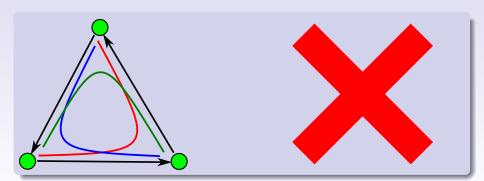
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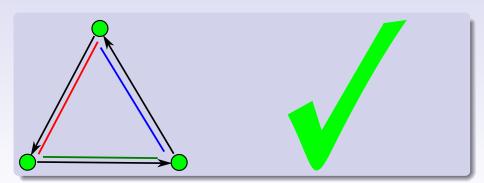
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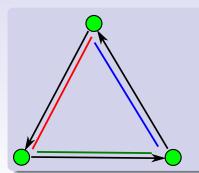
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- The feasibility of a configuration depends on the demands (routes), not on the used links.

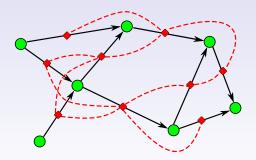
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- The feasibility of a configuration depends on the demands (routes), not on the used links.
- An efficient tool is needed to check whether a configuration is allowed or not.

Line graph

Definition (Line-Graph)

Let G = (V, A) be a directed graph. Its **line-graph** L(G) = (A, E) is an undirected graph the nodes of which correspond to the edges of G, and two nodes a_1 and a_2 are connected by an edge if and only if the head a_1 and the tail of a_2 is the same node in G, i.e.

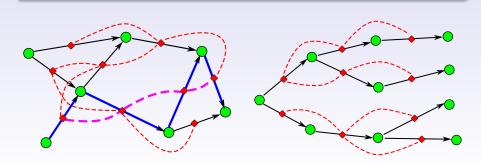
$$E := \{ (\overrightarrow{xu}, \overrightarrow{uy}) : x, y, u \in V \text{ and } \overrightarrow{xu}, \overrightarrow{uy} \in A \}$$
 (1)



Line graph of the routes

Line graph of paths and rooted trees

- The image L(p) of a path p of length k is a also path, which is of length k-1.
- If the length of p is 1, then L(p) is a single node in L(G).
- Similarly, a rooted *branching* T (i.e. a subtree with all edges directed oppositely to the root) naturally correspond the a forest (a set of disconnected trees) L(T) in L(G).



Line graph of patch and rooted trees

Theorem

A system $\{d_1, d_2, \ldots, d_k\}$ of demands/routes are assignable to one single wavelength light-mesh if and only if the union U of their images $L(d_1), L(d_2), \ldots, L(d_k)$ in the line graph forms a forest (i.e. an acyclic subgraph) in L(G).

Usage

Using this theorem one can easily check

- if a set of routes fit a single Light-mesh
- if a new route can be added to a Light-mesh

making it easy to implement heuristic optimization algorithms

Greedy Test (How many Light-meshes are needed for full connectivity

- Compute a full $n \times n$ routing using shortest paths.
- Add the paths one-by-one to the first Light-mesh where you can.
- If a path cannot be added to any of the existing Light-mesh, start a new one.

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Some "optimization"

- Pick up a Light-mesh
- Try to reallocate its all routes using the other Light-meshes
- If we could reallocate all routes, get rid of this Light-mesh.

A nice tool for implementing it (an advertisement)



http://lemon.cs.elte.hu

- An open source C++ template library targeting combinatorial optimization, especially problems related to graphs and networks.
- It is a member of the COIN-OR initiative, a collection of OR related open source projects.
- You are free to use it in your commercial or non-commercial applications under very permissive license terms.

```
    ▼ Terminal

Terminal
alpar@piko:~/projects/Papers/LightMesh/code/test>../build/mesh-pac
Add new wavelength: 1
Add new wavelength: 5
```

```
    ▼ Terminal

Terminal
```

```
    ▼ Terminal

Terminal
  .par@piko:~/projects/Papers/LightMesh/code/test>
```

```
    ▼ Terminal

Terminal
In color 9 there remained 119 paths (was: 395)
  .par@piko:~/projects/Papers/LightMesh/code/test>
```

Greedy Test (How many Light-meshes are needed for full connectivity

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Results

#node	10	20	50	100	200	500
# λ (greedy)	3	5	10	19	33	72
# λ ("optimized")	3	4	7	17	30	65

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Note

We didn't use any route optimization here, we just used what we got.

Optimal Slot Allocation in a Light Mesh

Claim

If there is a link used by k routes, at least k slots are necessary for a collision free allocation.

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Assume that the cyclic time frame is divided into S slots. Then, the routes can be assigned to the slots in a collision-free way if and only if each link is used by at most S routes.

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It is a vertex coloring problem in the line graph

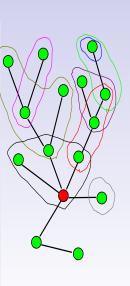
- The Light-mesh is a tree (forest) *T* in the line graph
- The routes correspond to subtrees $L(d_i) \subseteq T \quad (\forall d_i)$
- Goal:
 - assign a color to each subtree L(d_i) such that
 - for each vertex v, all the subtrees using v have different colors

Optimal Slot Allocation In a Light Mesh

Algorithm (Assign the routes to the slots)

```
1: Let T_1, T_2, \ldots, T_C be the connected components of F.
2: for all c = 1 to C do
3: Choose and arbitrary root vertex r_c \in T_c.
4: end for
5: for all di do
      Let a_i \in L(d_i) be the vertex that is the closest to
6:
       the root of its component.
      Let dist(i) be the distance between a and the root.
8: end for
9: for all vertices I in L(G) do
       Let free slots(I) be the list of available slots.
11: end for
12: for all d<sub>i</sub> in increasing order according to dist(i) do
13: Let s \in free slots(a_i).
14: Assign d_i to slot s_i.
15: for all I vertices in L(d_i) do
16:
          Remove s_i from free slots(I).
17:
     end for
```

18: end for



Optimal Slot Allocation In a Light Mesh

Thank you for the attention!